

# Numerical Relativity - PHY 6938

## Solutions to HW 8

1. a) In this problem we are trying to solve the PDE  $\partial_t u + \partial_x u = 0$ . This is a single mode with speed 1 moving to the right. I.e. on the left boundary ( $x = 0$ ) we need to specify a boundary condition to say what is coming in. On the right boundary ( $x = 1$ ) nothing can come in since the mode is moving to the right, so no BC is needed. In fact imposing one at  $x = 1$  may be incompatible with well-posedness and lead to instabilities.

Thus the program `advection1.py` is incorrect! It never changes the value of  $u$  at both boundaries. The reason is that `advection1.py` uses `D0` which simply does nothing at both ends. This is the same as imposing the BCs  $u(0, t) = 0$  and  $u(1, t) = \sin(1)$ . I.e. it imposes BCs at both ends! If you run `advection1.py` you will see that  $u$  develops growing spikes with the highest possible wavenumber of the grid. This is the hallmark of an instability, which is caused by using an ill-posed method.

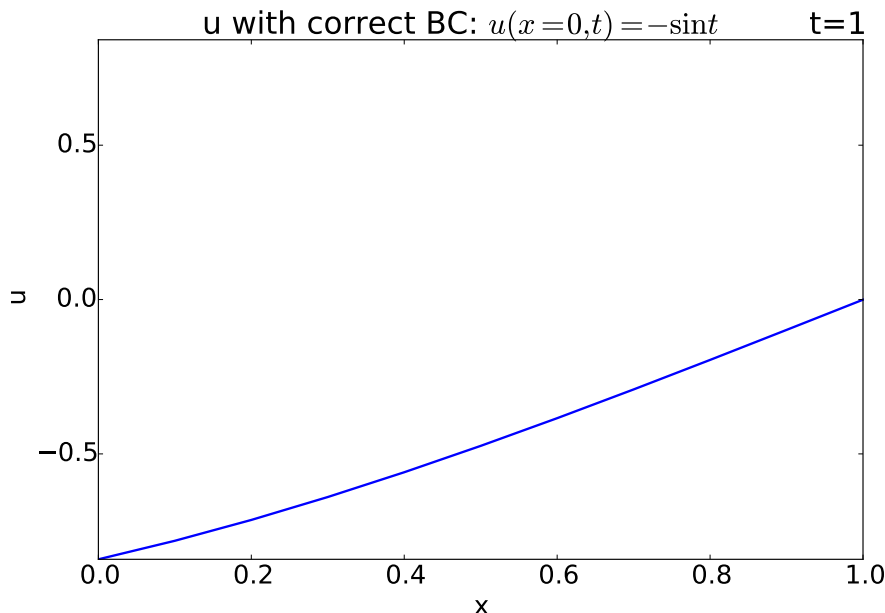
If we use `Dp` instead of `D0` things get worse. Now we are imposing  $u(1, t) = \sin(1)$  at the side where there should be no BC, because `Dp` does nothing at the right side. But on the left side we use  $\partial_t u + \partial_x u = 0$  because there `Dp` works just fine. I.e. on the left side we are not imposing a BC, even though we should.

If we use `Dm` instead of `D0` the program works fine. Now we are using  $\partial_t u + \partial_x u = 0$  on the right side because `Dm` works well there. While on the left we are using  $u(0, t) = 0$ , because we never change  $u$  there. Thus we get the case where the initial sinus function simply moves to the right, and nothing is coming in.

b) We should impose a BC only on the left side at  $x = 0$ .

c) In order to obtain  $\sin(x - t)$  we should impose  $u(0, t) = \sin(-t)$  on the left side and set the initial  $u$  to  $u(x, 0) = \sin(x)$  (as done already).

d) The new modified program and its output at  $t = 1$  is below:



```

# import some packages
from __future__ import print_function
import numpy as np

#####
# define some functions:
#####

# right deriv
def Dp(u, dx, du):
    for i in range(0, len(u)-1):
        du[i] = (u[i+1] - u[i])/dx

# left deriv
def Dm(u, dx, du):
    for i in range(1, len(u)):
        du[i] = (u[i] - u[i-1])/dx

# centered deriv
def D0(u, dx, du):
    for i in range(1, len(u)-1):
        du[i] = (u[i+1] - u[i-1])/(2.0*dx)

# RHS of  $\partial_t u$ 
def eval_rhs(u, dx, du):
    Dm(u, dx, du)
    return -du

#  $u(t+dt) = u(t) + \partial_t u * dt$ 
def calc_unew(u, rhs, dt):
    return u + rhs * dt

# nonsense BC at both ends
def set_BC_alt(u, dx, du, t, dt):
    u[0] = np.sin(-t)
    im = len(u)
    u[im-1] = np.sin(dx*(im-1) - t)

# BC at the side  $x=0$  where we have incoming modes
def set_BC(u, dx, du, t, dt):
    u[0] = np.sin(-t)

# print columns with data at time t
def pr_timeframe(t, x, u):
    print("# time =", t)
    for i in range(0, len(u)):
        print(x[i], u[i])
    print()

#####
# main program:
#####

# grid: 11 points from 0 to 1, i.e.  $x[0]=0, \dots, x[10]=1$ 
x = np.linspace(0, 1, 11)
dx = x[1]-x[0] # grid spacing
dt = 0.5*dx    # time step

# du will contain deriv of u, initialize to 0
du = np.zeros(len(x))

# initial u
t = 0.0
u = np.sin(x)
set_BC(u, dx, du, t, dt)
pr_timeframe(t, x, u)

timesteps = 20

```

```
# loop over time steps, and print results
for n in range(0, timesteps):
    # make time step, using simple Euler method
    t = t + dt
    rhs = eval_rhs(u, dx, du)
    u = calc_unew(u, rhs, dt)
    set_BC(u, dx, du, t, dt)
    # print columns with data
    pr_timeframe(t, x, u)
```